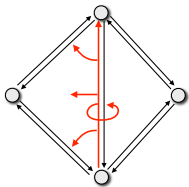
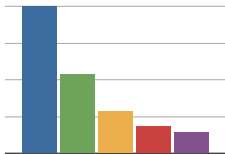


Design, Implementation, and Evaluation of the Surface_mesh Data Structure



```
class Surface_iterator  
{  
public:  
    // Default constructor  
    Surface_iterator(vertices) : m_idx(0)  
    {}  
    // Get to the vertex the iterator points to  
    operator vertices* const { return m_v; }  
    // Are two iterators equal?  
    operator bool() const { return m_idx == 0; }  
    // Are two iterators different?  
    operator bool() const { return m_idx != 0; }  
    // Get next iterator  
    operator Surface_iterator& operator++()  
    {  
        m_idx++;  
        return *this;  
    }  
    // Get previous iterator  
    operator Surface_iterator& operator--()  
    {  
        m_idx--;  
        return *this;  
    }  
private:  
    int m_idx;  
};
```



Daniel Sieger and Mario Botsch

Graphics & Geometry Processing Group
Bielefeld University
Germany

Outline

Introduction

Design

Implementation

Evaluation

Memory

Performance

Ease of Use

Conclusions

Introduction

Mesh data structures

- Fundamental for research and development
- Time-consuming to implement

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Existing libraries (Mesquite, CGAL, OpenMesh, ...)

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- Strengths and weaknesses

Introduction

Mesh data structures

- Fundamental for research and development
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Existing libraries (Mesquite, CGAL, OpenMesh, ...)

- Strengths and weaknesses
- Complexity
- Performance

Introduction

Our approach:

- Systematically analyze **design** choices
- Careful and efficient **implementation**
- Comprehensive **evaluation**

Outline

Introduction

Design

Implementation

Evaluation

Memory

Performance

Ease of Use

Conclusions

Design Goals

Compromise between

- Efficiency
- Memory
- Applicability
- Ease of use

Design Goals

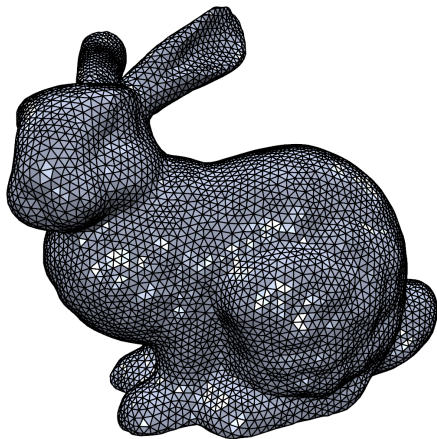
Compromise between

- Efficiency
- Memory
- Applicability
- **Ease of use**

Design Decisions

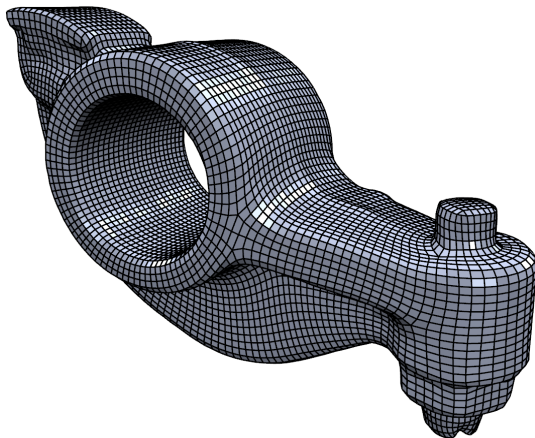
Element Types

Computer Graphics: triangle meshes



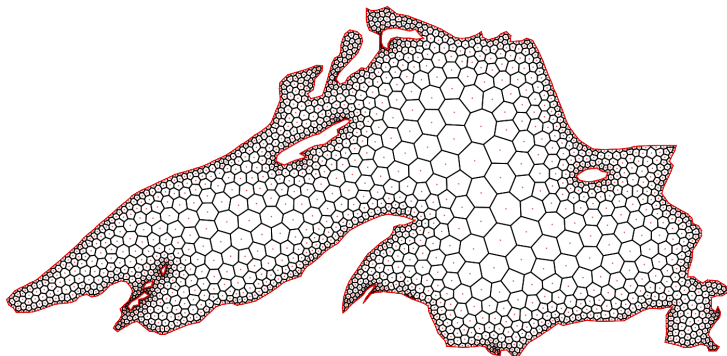
Element Types

Simulation: quad meshes



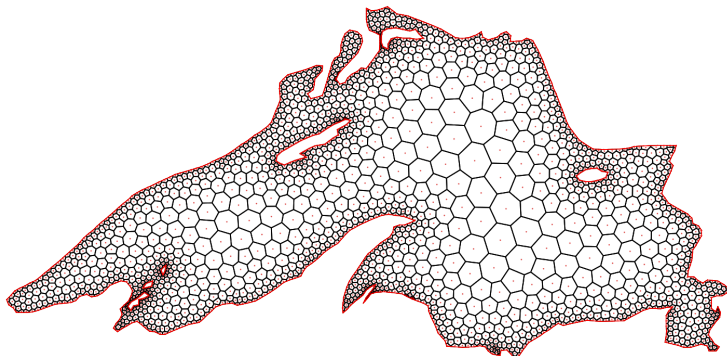
Element Types

Voronoi diagrams, Polygonal Finite Elements



Element Types

Voronoi diagrams, Polygonal Finite Elements



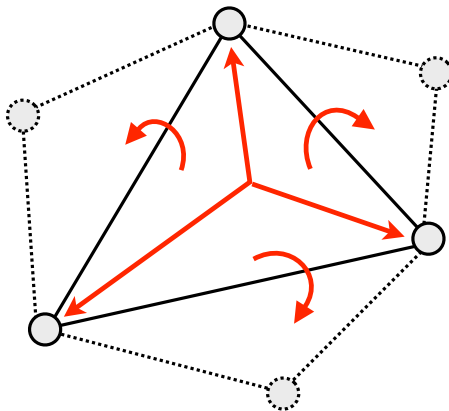
→ support arbitrary polygonal elements

Connectivity Representation

face-based vs. edge-based

Face-Based Representations

- Store faces and references to
 - Defining vertices
 - Neighboring faces



Face-Based Representations

Pros:

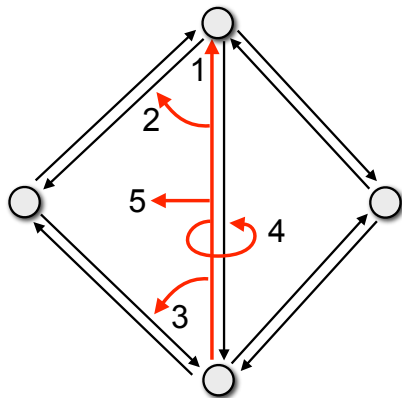
- + Simplicity
- + Memory consumption

Cons:

- Variable size data types
- One-ring traversal
- No explicit edges

Halfedge Data Structure

- Store pairs of oriented halfedges



1. Target vertex
2. Next halfedge
3. Previous halfedge
4. Opposite halfedge
5. Adjacent face

Halfedge Data Structure

Pros:

- + All entities and relations represented
- + Constant size data types
- + Efficient adjacency queries

Cons:

- Memory consumption

Halfedge Data Structure

Pros:

- + All entities and relations represented
- + Constant size data types
- + Efficient adjacency queries

Cons:

- Memory consumption

→ use a halfedge data structure

Storage Scheme

List-based

- + Easy removal
- Performance
- Memory consumption
- Memory layout

Storage Scheme

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Array-based

- + Performance
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- + Memory layout
- Garbage collection

Storage Scheme

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Array-based

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→ use array-based storage

Entity References

Pointers

- + Direct memory access
- Invalid upon resize
- Memory consumption

Indices

- + Validity checks
- + Memory consumption
- Indirect memory access

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→ use indices

Custom Properties

Extended entities

```
class Vertex
{
    Vec3 position;
    Vec3 normal;
    float weight;
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Vertex vertices[N];
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- Memory layout

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Vec3 positions[N];
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- Synchronization

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Synchronized arrays

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Vec3 positions[N];
Vec3 normals[N];
float weights[N];
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- + Dynamic at run-time
- + Memory layout
- Synchronization

→ use synchronized arrays

Ease of Use

Genericity

- + Customization
- Accessibility
- Documentation

Simplicity

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- + Documentation
- Customization

Ease of Use

Genericity

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Simplicity

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- Customization

→ strive for simplicity

Summary

Supported element types	→	arbitrary polygons
Connectivity representation	→	halfedges
Storage scheme	→	arrays
Entity references	→	indices
Custom properties	→	synchronized arrays
Ease of use	→	simplicity

Outline

Introduction

Design

Implementation

Evaluation

Memory

Performance

Ease of Use

Conclusions

Implementation Overview

- Based on OpenMesh

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- Massively simplified
- Single class, no complicated hierarchy
- Templates reduced to a minimum

Implementation Overview

- Based on OpenMesh
- Massively simplified
- Single class, no complicated hierarchy
- Templates reduced to a minimum
- OpenMesh: 8400 lines of code
- `Surface_mesh` : 2250 lines of code

Example: Smoothing

```
#include <Surface_mesh.h>

int main(int argc, char** argv)
{
    Surface_mesh mesh;

    mesh.read(argv[1]);

    Vertex_property<Point> points = mesh.get_vertex_property<Point>("v:point");
    Vertex_iterator vit, vend = mesh.vertices_end();
    Vertex_around_vertex_circulator vc, vc_end;

    for (vit = mesh.vertices_begin(); vit != vend; ++vit)
    {
        Point p(0,0,0);
        Scalar c(0);
        vc = vc_end = mesh.vertices(*vit);
        do
        {
            p += points[*vc];
            ++c;
        }
        while (++vc != vc_end);
        points[*vit] = p / c;
    }

    mesh.write(argv[2]);
}
```

Outline

Introduction

Design

Implementation

Evaluation

Memory

Performance

Ease of Use

Conclusions

Evaluation Overview

Libraries:

- Mesquite
- CGAL
- OpenMesh

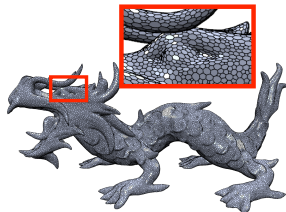
Models



Imp Model
300k vertices, 600k triangles



Lucy Model
10M vertices, 20M triangles



Dual Dragon Model
100k vertices, 50k polygons

Outline

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Design

Implementation

Evaluation

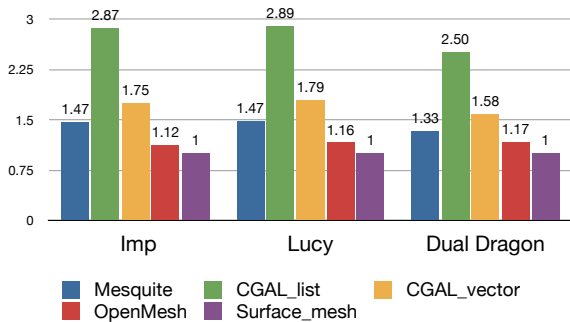
Memory

Performance

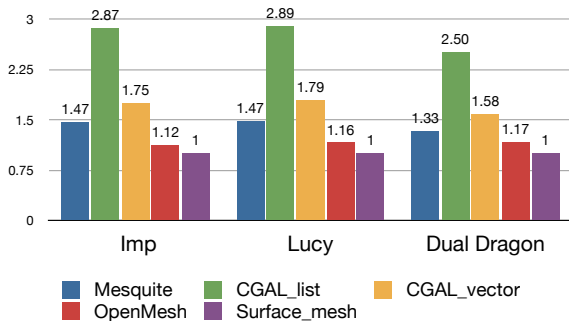
Ease of Use

Conclusions

Memory Consumption



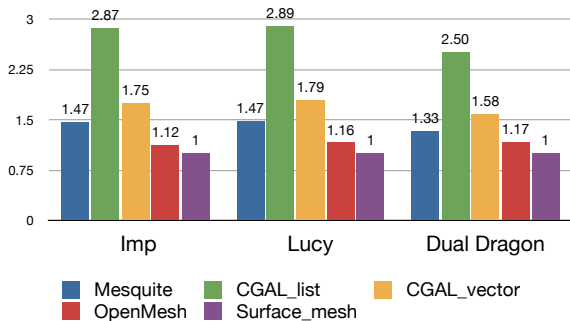
Memory Consumption



Mesquite

- Variable storage
- 64-bit references
- Helper data

Memory Consumption



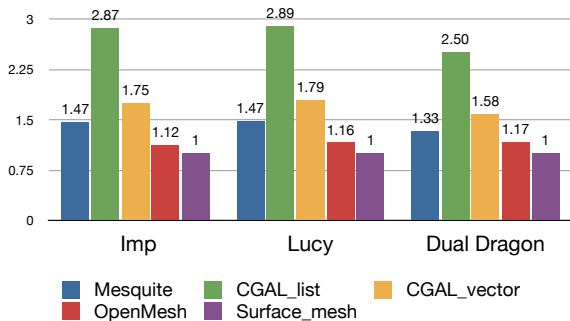
Mesquite

- Variable storage
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CGAL

- 64-bit references
- List: Generally higher

Memory Consumption



Mesquite

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CGAL

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OpenMesh

- Status information

Outline

Introduction

Design

Implementation

Evaluation

Memory

Performance

Ease of Use

Conclusions

Benchmarks Overview

Circulator Faces around vertex, vertices around face

Benchmarks Overview

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Barycenter Compute barycenter of vertices

Benchmarks Overview

- Circulator** Faces around vertex, vertices around face
- Barycenter** Compute barycenter of vertices
- Normals** Compute and store face & vertex normals

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- Circulator** Faces around vertex, vertices around face
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- Normals** Compute and store face & vertex normals
- Smoothing** Move vertices to barycenter of neighbors

Benchmarks Overview

Circulator Faces around vertex, vertices around face

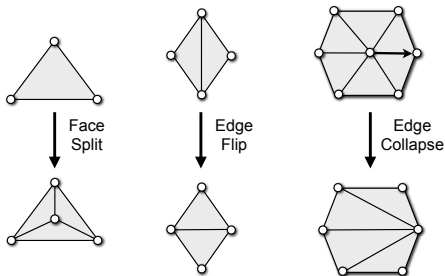
Barycenter Compute barycenter of vertices

Normals Compute and store face & vertex normals

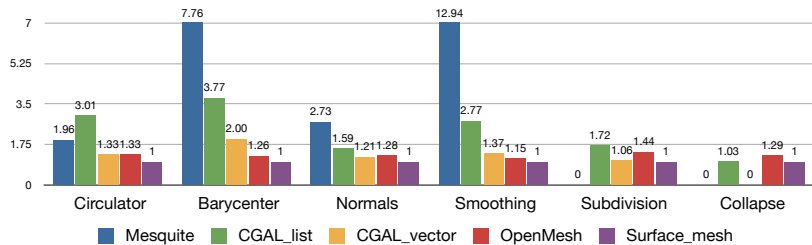
Smoothing Move vertices to barycenter of neighbors

Subdivision Face split & edge flip

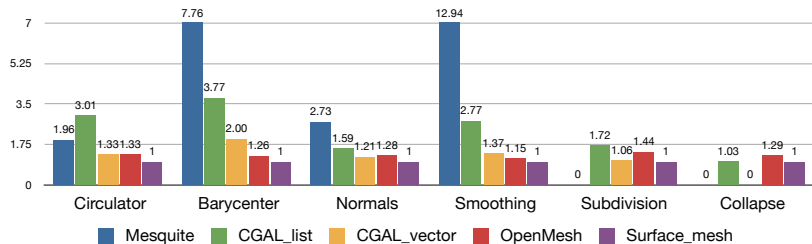
Collapse Face split & edge collapse



Results: Imp Model



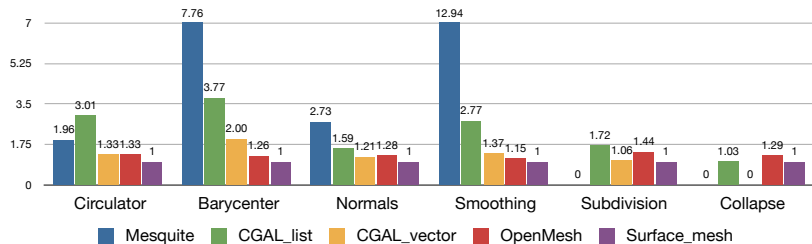
Results: Imp Model



Mesquite

- Virtual functions
- One-ring traversal
- Variable storage
- No topology changes

Results: Imp Model



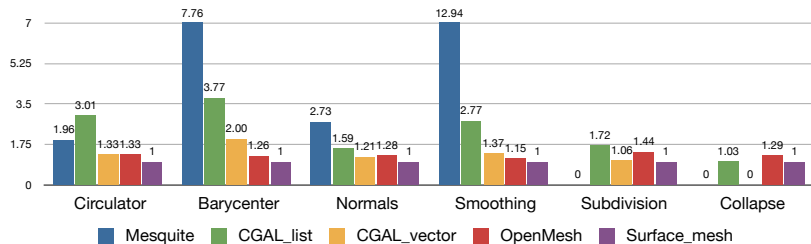
Mesquite

- Virtual functions
- One-ring traversal
- Variable storage
- No topology changes

CGAL

- Extended entities
- List: Memory layout
- Vector: No removal

Results: Imp Model



Mesquite

- Virtual functions
- One-ring traversal
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CGAL

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OpenMesh

- Circulators
- Properties

Outline

Introduction

Design

Implementation

Evaluation

Memory

Performance

Ease of Use

Conclusions

Simplicity & Properties

Working with a custom edge property in Surface_mesh

```
Surface_mesh mesh;  
  
// allocate property storing a point per edge  
Edge_property<Point> edge_points  
    = mesh.add_edge_property<Point>("property-name");  
  
// access the edge property like an array  
Edge e;  
edge_points[e] = Point(x,y,z);  
  
// remove property and free memory  
mesh.remove_edge_property(edge_points);
```

Simplicity & Properties

Just declaring a custom edge property in CGAL

```
typedef CGAL::Simple_cartesian<double>   Kernel;
typedef Kernel::Point_3                   Point_3;

template <class Refs> struct My_halfedge
  : public CGAL::HalfedgeDS_halfedge_base<Refs>
{
    Point_3 halfedge_point;
};

class Items : public CGAL::Polyhedron_items_3
{
public:
    template <class Refs, class Traits>
    struct Halfedge_wrapper
    {
        typedef My_halfedge<Refs> Halfedge;
    };
};

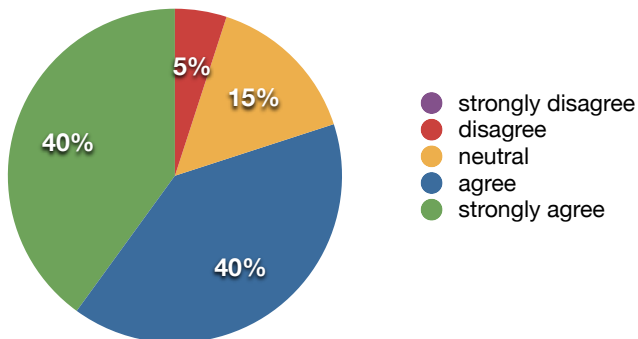
typedef CGAL::Polyhedron_3<Kernel, Items> Mesh;
```

User Feedback

- SGP 2011 graduate course on geometric modeling
- 18 participants, varying experience
- Q: Is `Surface_mesh` easy to use and understand?

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User Feedback: Comments

“It is easy to use for users that have experience with CGAL or OpenMesh. It is nice to have a template-free structure.”

“Much easier than OpenMesh.”

“I thought the data structure was quite easy to understand even though I have never worked with a real mesh data structure before.”

Outline

Introduction

Design

Implementation

Evaluation

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Our approach:

- Systematically analyze **design** choices
- Careful and efficient **implementation**
- Comprehensive **evaluation**

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- Easy to use
- Highly efficient
- Low memory consumption

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Our implementation of `Surface_mesh` :

- Easy to use
- Highly efficient
- Low memory consumption

Other libraries:

- Much more functionality beyond a pure data structure

Limitations & Future Work

Limitations:

- Single `Surface_mesh` declaration in one application
- Two-manifold surface meshes only

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Future work:

- Volumetric meshes

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Limitations:

- Single `Surface_mesh` declaration in one application
- Two-manifold surface meshes only

Future work:

- Volumetric meshes
- Include more libraries (VCGLib, LR, yours?)
- Establish standard set of benchmarks

→ <http://graphics.uni-bielefeld.de>

Thanks

... for your attention.